

HYPERSURFACES OF PRESCRIBED MEAN CURVATURE IN LORENTZIAN MANIFOLDS

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ABSTRACT. We give a new existence proof for closed hypersurfaces of prescribed mean curvature in Lorentzian manifolds.

0. INTRODUCTION

Hypersurfaces of prescribed mean curvature especially those with constant mean curvature play an important role in general relativity. In [3] the existence of closed hypersurfaces of prescribed mean curvature in a globally hyperbolic Lorentz manifold with a compact Cauchy hypersurface was proved provided there were barriers. The proof consisted of two parts, the a priori estimates for the gradient and the application of a fixed point theorem. That latter part of the proof was rather complicated, and certainly nobody would have qualified it as elegant.

Ecker and Huisken, therefore, gave another existence proof using an evolutionary approach, but they had to assume that the time-like convergence condition is satisfied, and, even more important, that the prescribed mean curvature satisfies a structural monotonicity condition, cf. [2]. These are serious restrictions which had to be assumed because the authors relied on the gradient estimate of Bartnik [1], who had proved another a priori estimate in the elliptic case.

We shall show in the following that the evolutionary method can be used in the existence proof without any unnecessary restrictions on the curvature of the ambient space or the right-hand side. The only difference in the assumptions—relative to our former paper—is that the right-hand side is now supposed to be of class C^1 , while bounded is actually sufficient. But this drawback can easily be overcome by approximation.

This paper is organized as follows: In Section 1 we introduce the notations and definitions we rely on.

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In Section 2 we look at the curvature flow associated with our problem, and the corresponding evolution equations for the basic geometric quantities of the flow hypersurfaces.

In Section 3 lower order estimates for the evolution problem are proved, while a priori estimates in the C^2 -norm are derived in Section 4.

Finally, in Section 5, we demonstrate that the evolutionary solution converges to a stationary solution.

1. NOTATIONS AND DEFINITIONS

The main objective of this section is to state the equations of Gauß, Codazzi, and Weingarten for hypersurfaces M in a $(n+1)$ -dimensional Lorentzian space N . Geometric quantities in N will be denoted by $(\bar{g}_{\alpha\beta})$, $(\bar{R}_{\alpha\beta\gamma\delta})$, etc., and those in M by (g_{ij}) , (R_{ijkl}) , etc. Greek indices range from 0 to n and Latin from 1 to n ; the summation convention is always used. Generic coordinate systems in N resp. M will be denoted by (x^α) resp. (ξ^i) . Covariant differentiation will simply be indicated by indices, only in case of possible ambiguity they will be preceded by a semicolon, i.e. for a function u in N , (u_α) will be the gradient and $(u_{\alpha\beta})$ the Hessian, but e.g., the covariant derivative of the curvature tensor will be abbreviated by $\bar{R}_{\alpha\beta\gamma\delta;\epsilon}$. We also point out that

$$(1.1) \quad \bar{R}_{\alpha\beta\gamma\delta;i} = \bar{R}_{\alpha\beta\gamma\delta;\epsilon} x_i^\epsilon$$

with obvious generalizations to other quantities.

Let M be a *space-like* hypersurface, i.e. the induced metric is Riemannian, with a differentiable normal ν that is time-like.

In local coordinates, (x^α) and (ξ^i) , the geometric quantities of the space-like hypersurface M are connected through the following equations

$$(1.2) \quad x_{ij}^\alpha = h_{ij} \nu^\alpha$$

the so-called *Gauß formula*. Here, and also in the sequel, a covariant derivative is always a *full* tensor, i.e.

$$(1.3) \quad x_{ij}^\alpha = x_{,ij}^\alpha - \Gamma_{ij}^k x_k^\alpha + \bar{\Gamma}_{\beta\gamma}^\alpha x_i^\beta x_j^\gamma.$$

The comma indicates ordinary partial derivatives.

In this implicit definition the *second fundamental form* (h_{ij}) is taken with respect to ν .

The second equation is the *Weingarten equation*

$$(1.4) \quad \nu_i^\alpha = h_i^k x_k^\alpha,$$

where we remember that ν_i^α is a full tensor.

Finally, we have the *Codazzi equation*

$$(1.5) \quad h_{ij;k} - h_{ik;j} = \bar{R}_{\alpha\beta\gamma\delta} \nu^\alpha x_i^\beta x_j^\gamma x_k^\delta$$

and the *Gauß equation*

$$(1.6) \quad R_{ijkl} = -\{h_{ik}h_{jl} - h_{il}h_{jk}\} + \bar{R}_{\alpha\beta\gamma\delta} x_i^\alpha x_j^\beta x_k^\gamma x_l^\delta.$$

Now, let us assume that N is a globally hyperbolic Lorentzian manifold with a *compact* Cauchy surface. N is then a topological product $\mathbb{R} \times \mathcal{S}_0$, where \mathcal{S}_0 is a compact Riemannian manifold, and there exists a Gaussian coordinate system (x^α) , such that the metric in N has the form

$$(1.7) \quad d\bar{s}_N^2 = e^{2\psi} \{-dx^0{}^2 + \sigma_{ij}(x^0, x) dx^i dx^j\},$$

where σ_{ij} is a Riemannian metric, ψ a function on N , and x an abbreviation for the space-like components (x^i) , see [8], [10, p. 212], [9, p. 252], and [3, Section 6]. We also assume that the coordinate system is *future oriented*, i.e. the time coordinate x^0 increases on future directed curves. Hence, the *contravariant* time-like vector $(\xi^\alpha) = (1, 0, \dots, 0)$ is future directed as is its *covariant* version $(\xi_\alpha) = e^{2\psi}(-1, 0, \dots, 0)$.

Let $M = \text{graph } u|_{\mathcal{S}_0}$ be a space-like hypersurface

$$(1.8) \quad M = \{(x^0, x) : x^0 = u(x), x \in \mathcal{S}_0\},$$

then the induced metric has the form

$$(1.9) \quad g_{ij} = e^{2\psi} \{-u_i u_j + \sigma_{ij}\}$$

where σ_{ij} is evaluated at (u, x) , and its inverse $(g^{ij}) = (g_{ij})^{-1}$ can be expressed as

$$(1.10) \quad g^{ij} = e^{-2\psi} \left\{ \sigma^{ij} + \frac{u^i u^j}{v} \right\},$$

where $(\sigma^{ij}) = (\sigma_{ij})^{-1}$ and

$$(1.11) \quad \begin{aligned} u^i &= \sigma^{ij} u_j \\ v^2 &= 1 - \sigma^{ij} u_i u_j \equiv 1 - |Du|^2. \end{aligned}$$

Hence, graph u is space-like if and only if $|Du| < 1$.

The covariant form of a normal vector of a graph looks like

$$(1.12) \quad (\nu_\alpha) = \pm v^{-1} e^\psi (1, -u_i).$$

and the contravariant version is

$$(1.13) \quad (\nu^\alpha) = \mp v^{-1} e^{-\psi} (1, u^i).$$

Thus, we have

REMARK 1.1. Let M be space-like graph in a future oriented coordinate system. Then, the contravariant future directed normal vector has the form

$$(1.14) \quad (\nu^\alpha) = v^{-1}e^{-\psi}(1, u^i)$$

and the past directed

$$(1.15) \quad (\nu^\alpha) = -v^{-1}e^{-\psi}(1, u^i).$$

In the Gauß formula (1.2) we are free to choose the future or past directed normal, but we stipulate that we always use the past directed normal for reasons that we have explained in [6].

Look at the component $\alpha = 0$ in (1.2) and obtain in view of (1.15)

$$(1.16) \quad e^{-\psi}v^{-1}h_{ij} = -u_{ij} - \bar{\Gamma}_{00}^0 u_i u_j - \bar{\Gamma}_{0j}^0 u_i - \bar{\Gamma}_{0i}^0 u_j - \bar{\Gamma}_{ij}^0.$$

Here, the covariant derivatives are taken with respect to the induced metric of M , and

$$(1.17) \quad -\bar{\Gamma}_{ij}^0 = e^{-\psi}\bar{h}_{ij},$$

where (\bar{h}_{ij}) is the second fundamental form of the hypersurfaces $\{x^0 = \text{const}\}$.

An easy calculation shows

$$(1.18) \quad \bar{h}_{ij}e^{-\psi} = -\frac{1}{2}\dot{\sigma}_{ij} - \dot{\psi}\sigma_{ij},$$

where the dot indicates differentiation with respect to x^0 .

Next, let us analyze under which condition a space-like hypersurface M can be written as a graph over the Cauchy hypersurface \mathcal{S}_0 .

We first need

DEFINITION 1.2. Let M be a closed, space-like hypersurface in N . Then,

- (i) M is said to be *achronal*, if no two points in M can be connected by a future directed time-like curve.
- (ii) M is said to *separate* N , if $N \setminus M$ is disconnected.

In [6, Proposition 2.5] we proved

PROPOSITION 1.3. Let N be connected and globally hyperbolic, $\mathcal{S}_0 \subset N$ a compact Cauchy hypersurface, and $M \subset N$ a compact, connected space-like hypersurface of class C^m , $m \geq 1$. Then, $M = \text{graph } u|_{\mathcal{S}_0}$ with $u \in C^m(\mathcal{S}_0)$ iff M is achronal.

Sometimes, we need a Riemannian reference metric, e.g. if we want to estimate tensors. Since the Lorentzian metric can be expressed as

$$(1.19) \quad \bar{g}_{\alpha\beta}dx^\alpha dx^\beta = e^{2\psi}\{-dx^{02} + \sigma_{ij}dx^i dx^j\},$$

we define a Riemannian reference metric $(\tilde{g}_{\alpha\beta})$ by

$$(1.20) \quad \tilde{g}_{\alpha\beta} dx^\alpha dx^\beta = e^{2\psi} \{ dx^{02} + \sigma_{ij} dx^i dx^j \}$$

and we abbreviate the corresponding norm of a vectorfield η by

$$(1.21) \quad \|\eta\| = (\tilde{g}_{\alpha\beta} \eta^\alpha \eta^\beta)^{1/2},$$

with similar notations for higher order tensors.

2. THE EVOLUTION PROBLEM

Let N be a globally hyperbolic Lorentzian manifold with a compact Cauchy hypersurface \mathcal{S}_0 . Consider the problem of finding a closed hypersurface of prescribed mean curvature H in N , or more precisely, let Ω be a connected open subset of N , $f \in C^{0,\alpha}(\bar{\Omega})$, then we look for a hypersurface $M \subset \Omega$ such that

$$(2.1) \quad H|_M = f(x) \quad \forall x \in M,$$

where $H|_M$ means that H is evaluated at the vector $(\kappa_i(x))$ the components of which are the principal curvatures of M .

We assume that $\partial\Omega$ consists of two achronal, compact, connected, space-like hypersurfaces M_1 and M_2 , where M_1 is supposed to lie in the *past* of M_2 . The M_i should act as barriers for (H, f) .

DEFINITION 2.1. M_2 is an *upper barrier* for (H, f) , if M_2 is of class $C^{2,\alpha}$ and

$$(2.2) \quad H|_{M_2} \geq f,$$

and M_1 is a *lower barrier* for (H, f) , if M_1 is of class $C^{2,\alpha}$ satisfying

$$(2.3) \quad H|_{M_1} \leq f.$$

In [3, Section 6] we proved the following theorem

THEOREM 2.2. *Let M_1 be a lower and M_2 be an upper barrier for (H, f) , $f \in C^{0,\alpha}(\bar{\Omega})$. Then, the problem*

$$(2.4) \quad H|_M = f$$

has a solution $M \subset \bar{\Omega}$ of class $C^{2,\alpha}$ that can be written as a graph over the Cauchy hypersurface \mathcal{S}_0 .

The crucial point in the proof is an a priori estimate in the C^1 -norm and for this estimate only the boundedness of f is needed, i.e. even for merely bounded f $H^{2,p}$ solutions exist.

We want to give a new proof of Theorem 2.2 that is based on the evolution method, and to make this method work, we have to assume temporarily slightly higher degrees of regularity for the barriers and right-hand side, i.e. we assume the barriers to be of class $C^{4,\alpha}$ and f to

be of class $C^{2,\alpha}$. We can achieve these assumptions by approximation without sacrificing the barrier conditions, cf. [5, p. 179].

To solve (2.4) we look at the evolution problem

$$(2.5) \quad \begin{aligned} \dot{x} &= (H - f)\nu, \\ x(0) &= x_0, \end{aligned}$$

where x_0 is an embedding of an initial hypersurface M_0 , for which we choose $M_0 = M_2$, H is the mean curvature of the flow hypersurfaces $M(t)$ with respect to the past directed normal ν , and $x(t)$ is an embedding of $M(t)$.

In [6] we have considered problems of the form (2.5) for general curvature operators in a pseudo-riemannian setting, so that the present situation can be retrieved as a special case of the general results in [6, Section 3].

The evolution exists on a maximal time interval $[0, T^*)$, $0 < T^* \leq \infty$, cf. [4, Section 2], where we apologize for the ambiguity of also calling the evolution parameter *time*.

Next, we want to show how the metric, the second fundamental form, and the normal vector of the hypersurfaces $M(t)$ evolve. All time derivatives are *total* derivatives. We refer to [6] for more general results and to [4, Section 3], where proofs are given in a Riemannian setting, but these proofs are also valid in a Lorentzian environment.

LEMMA 2.3. *The metric, the normal vector, and the second fundamental form of $M(t)$ satisfy the evolution equations*

$$(2.6) \quad \dot{g}_{ij} = 2(H - f)h_{ij},$$

$$(2.7) \quad \dot{\nu} = \nabla_M(H - f) = g^{ij}(H - f)_i x_j,$$

and

$$(2.8) \quad \dot{h}_i^j = (H - f)_i^j - (H - f)h_i^k h_k^j - (H - f)\bar{R}_{\alpha\beta\gamma\delta}\nu^\alpha x_i^\beta \nu^\gamma x_k^\delta g^{kj}$$

$$(2.9) \quad \dot{h}_{ij} = (H - f)_{ij} + (H - f)h_i^k h_{kj} - (H - f)\bar{R}_{\alpha\beta\gamma\delta}\nu^\alpha x_i^\beta \nu^\gamma x_j^\delta.$$

LEMMA 2.4 (EVOLUTION OF $(H - f)$). *The term $(H - f)$ evolves according to the equation*

$$(2.10) \quad \begin{aligned} (H - f)' - \Delta(H - f) &= -\|A\|^2(H - f) - f_\alpha \nu^\alpha (H - f) \\ &\quad - \bar{R}_{\alpha\beta} \nu^\alpha \nu^\beta (H - f), \end{aligned}$$

where

$$(2.11) \quad (H - f)' = \frac{d}{dt}(H - f)$$

and

$$(2.12) \quad \|A\|^2 = h_{ij}h^{ij}.$$

From (2.8) we deduce with the help of the Ricci identities a parabolic equation for the second fundamental form

LEMMA 2.5. *The mixed tensor h_i^j satisfies the parabolic equation*

$$(2.13) \quad \begin{aligned} \dot{h}_i^j - \Delta h_i^j &= -\|A\|^2 h_i^j + f h_i^k h_k^j - f_{\alpha\beta} x_i^\alpha x_k^\beta g^{kj} - f_\alpha \nu^\alpha h_i^j \\ &\quad + 2\bar{R}_{\alpha\beta\gamma\delta} x_m^\alpha x_i^\beta x_k^\gamma x_r^\delta h^{km} g^{rj} \\ &\quad - g^{kl} \bar{R}_{\alpha\beta\gamma\delta} x_m^\alpha x_k^\beta x_r^\gamma x_l^\delta h_i^m g^{rj} - g^{kl} \bar{R}_{\alpha\beta\gamma\delta} x_m^\alpha x_k^\beta x_i^\gamma x_l^\delta h^{mj} \\ &\quad - \bar{R}_{\alpha\beta} \nu^\alpha \nu^\beta h_i^j + f \bar{R}_{\alpha\beta\gamma\delta} \nu^\alpha x_i^\beta \nu^\gamma x_m^\delta g^{mj} \\ &\quad + g^{kl} \bar{R}_{\alpha\beta\gamma\delta;\epsilon} \{ \nu^\alpha x_k^\beta x_l^\gamma x_i^\delta x_m^\epsilon g^{mj} + \nu^\alpha x_i^\beta x_k^\gamma x_m^\delta x_l^\epsilon g^{mj} \}. \end{aligned}$$

REMARK 2.6. In view of the maximum principle, we immediately deduce from (2.10) that the term $(H - f)$ has a sign during the evolution if it has one at the beginning. Thus, we have

$$(2.14) \quad H \geq f.$$

3. LOWER ORDER ESTIMATES

We recall our assumption that the ambient space is globally hyperbolic with a compact Cauchy hypersurface \mathcal{S}_0 . The barriers M_i are then graphs over \mathcal{S}_0 , $M_i = \text{graph } u_i$, because they are achronal, cf. Proposition 1.3, and we have

$$(3.1) \quad u_1 \leq u_2,$$

for M_1 should lie in the past of M_2 , and the enclosed domain is supposed to be connected. Moreover, in view of the Harnack inequality, the strict inequality is valid in (3.1) unless the barriers coincide and are a solution to our problem.

Let us look at the evolution equation (2.5) with initial hypersurface M_0 equal to M_2 . Then, because of the short-time existence, the evolution will exist on a maximal time interval $I = [0, T^*)$, $T^* \leq \infty$, as long as the evolving hypersurfaces are space-like and smooth.

Furthermore, since the initial hypersurface is a graph over \mathcal{S}_0 , we can write

$$(3.2) \quad M(t) = \text{graph } u(t)|_{\mathcal{S}_0} \quad \forall t \in I,$$

where u is defined in the cylinder $Q_{T^*} = I \times \mathcal{S}_0$. We then deduce from (2.5), looking at the component $\alpha = 0$, that u satisfies a parabolic

equation of the form

$$(3.3) \quad \dot{u} = -e^{-\psi} v^{-1} (H - f),$$

where we use the notations in Section 1, and where we emphasize that the time derivative is a total derivative, i.e.

$$(3.4) \quad \dot{u} = \frac{\partial u}{\partial t} + u_i \dot{x}^i.$$

Since the past directed normal can be expressed as

$$(3.5) \quad (\nu^\alpha) = -e^{-\psi} v^{-1} (1, u^i),$$

we conclude from (2.5), (3.3), and (3.4)

$$(3.6) \quad \frac{\partial u}{\partial t} = -e^{-\psi} v (H - f).$$

Thus, $\frac{\partial u}{\partial t}$ is non-positive in view of Remark 2.6.

Next, let us state our first a priori estimate

LEMMA 3.1. *During the evolution the flow hypersurfaces stay in $\bar{\Omega}$.*

This is an immediate consequence of the Harnack inequality, cf. [4, Lemma 5.1] for details.

As a consequence of Lemma 3.1 we obtain

$$(3.7) \quad \inf_{S_0} u_1 \leq u \leq \sup_{S_0} u_2 \quad \forall t \in I.$$

We are now able to derive the C^1 -estimates, i.e. we shall show that the hypersurfaces remain uniformly space-like, or equivalently, that the term

$$(3.8) \quad \tilde{v} = v^{-1} = \frac{1}{\sqrt{1 - |Du|^2}}$$

is uniformly bounded.

Let us first derive an evolution equation for \tilde{v} .

LEMMA 3.2 (EVOLUTION OF \tilde{v}). *Consider the flow (2.5) in the distinguished coordinate system associated with S_0 . Then, \tilde{v} satisfies the evolution equation*

$$(3.9) \quad \begin{aligned} \dot{\tilde{v}} - \Delta \tilde{v} = & - \|A\|^2 \tilde{v} - f \eta_{\alpha\beta} \nu^\alpha \nu^\beta - f_\beta x_i^\beta \eta_\alpha x_k^\alpha g^{ik} \\ & - 2h^{ij} x_i^\alpha x_j^\beta \eta_{\alpha\beta} - g^{ij} \eta_{\alpha\beta\gamma} x_i^\beta x_j^\gamma \nu^\alpha \\ & - \bar{R}_{\alpha\beta} \nu^\alpha x_k^\beta \eta_\gamma x_l^\gamma g^{kl}, \end{aligned}$$

where η is the covariant vector field $(\eta_\alpha) = e^\psi (-1, 0, \dots, 0)$.

Proof. We have $\tilde{v} = \langle \eta, \nu \rangle$. Let (ξ^i) be local coordinates for $M(t)$. Differentiating \tilde{v} covariantly we deduce

$$(3.10) \quad \tilde{v}_i = \eta_{\alpha\beta} x_i^\beta \nu^\alpha + \eta_\alpha \nu_i^\alpha,$$

$$(3.11) \quad \begin{aligned} \tilde{v}_{ij} &= \eta_{\alpha\beta\gamma} x_i^\beta x_j^\gamma \nu^\alpha + \eta_{\alpha\beta} x_{ij}^\beta \nu^\alpha \\ &\quad + \eta_{\alpha\beta} x_i^\beta \nu_j^\alpha + \eta_{\alpha\beta} x_j^\beta \nu_i^\alpha + \eta_\alpha \nu_{ij}^\alpha \end{aligned}$$

The time derivative of \tilde{v} can be expressed as

$$(3.12) \quad \begin{aligned} \dot{\tilde{v}} &= \eta_{\alpha\beta} \dot{x}^\beta \nu^\alpha + \eta_\alpha \dot{\nu}^\alpha \\ &= \eta_{\alpha\beta} \nu^\alpha \nu^\beta (H - f) + (H - f)^k x_k^\alpha \eta_\alpha \\ &= \eta_{\alpha\beta} \nu^\alpha \nu^\beta (H - f) + H^k x_k^\alpha \eta_\alpha - f_\beta x_i^\beta x_k^\alpha g^{ik} \eta_\alpha, \end{aligned}$$

where we have used (2.7).

Substituting (3.11) and (3.12) in (3.9), and simplifying the resulting equation with the help of the Weingarten and Codazzi equations, we arrive at the desired conclusion. q.e.d.

LEMMA 3.3. *There is a constant $c = c(\Omega)$ such that for any positive function $0 < \epsilon = \epsilon(x)$ on \mathcal{S}_0 and any hypersurface $M(t)$ of the flow we have*

$$(3.13) \quad \|\nu\| \leq c\tilde{v},$$

$$(3.14) \quad g^{ij} \leq c\tilde{v}^2 \sigma^{ij},$$

and

$$(3.15) \quad |h^{ij} \eta_{\alpha\beta} x_i^\alpha x_j^\beta| \leq \frac{\epsilon}{2} \|A\|^2 \tilde{v} + \frac{c}{2\epsilon} \tilde{v}^3$$

where (η_α) is the vector field in Lemma 3.2.

Proof. The first two estimates can be immediately verified. To prove (3.15) we choose local coordinates (ξ^i) such that

$$(3.16) \quad h_{ij} = \kappa_i \delta_{ij}, \quad g_{ij} = \delta_{ij}$$

and deduce

$$(3.17) \quad \begin{aligned} |h^{ij} \eta_{\alpha\beta} x_i^\alpha x_j^\beta| &\leq \sum_i |\kappa_i| |\eta_{\alpha\beta} x_i^\alpha x_i^\beta| \\ &\leq \frac{\epsilon}{2} \|A\|^2 \tilde{v} + \frac{1}{2\epsilon} \tilde{v}^{-1} \sum_i |\eta_{\alpha\beta} x_i^\alpha x_i^\beta|^2, \end{aligned}$$

and

$$(3.18) \quad \sum_i |\eta_{\alpha\beta} x_i^\alpha x_i^\beta|^2 \leq g^{ik} \eta_{\alpha\beta} x_i^\alpha x_j^\beta g^{jl} \eta_{\gamma\delta} x_k^\gamma x_l^\delta.$$

Hence, the result in view of (3.14). q.e.d.

Combining the preceding lemmata we infer

LEMMA 3.4. *There is a constant $c = c(\Omega)$ such that for any positive function $\epsilon = \epsilon(x)$ on \mathcal{S}_0 the term \tilde{v} satisfies a parabolic inequality of the form*

$$(3.19) \quad \dot{\tilde{v}} - \Delta \tilde{v} \leq -(1 - \epsilon) \|A\|^2 \tilde{v} + c[|f| + \|Df\|] \tilde{v}^2 + c[1 + \epsilon^{-1}] \tilde{v}^3.$$

We note that the statement c depends on Ω also implies that c depends on geometric quantities of the ambient space restricted to Ω .

We further need the following two lemmata

LEMMA 3.5. *Let $M(t) = \text{graph } u(t)$ be the flow hypersurfaces, then we have*

$$(3.20) \quad \dot{u} - \Delta u = e^{-\psi} v^{-1} f - e^{-\psi} g^{ij} \bar{h}_{ij} + \bar{\Gamma}_{00}^0 \|Du\|^2 + 2\bar{\Gamma}_{0i}^0 u^i,$$

where the time derivative is a total derivative.

Proof. We use the relation

$$(3.21) \quad \dot{u} = -e^{-\psi} v^{-1} (H - f)$$

together with (1.16). q.e.d.

LEMMA 3.6. *Let $M \subset \bar{\Omega}$ be a graph over \mathcal{S}_0 , $M = \text{graph } u$, then*

$$(3.22) \quad |\tilde{v}_i u^i| \leq c \tilde{v}^3 + \|A\| e^\psi \|Du\|^2,$$

where $c = c(\Omega)$.

Proof. First, we use that

$$(3.23) \quad \tilde{v}^2 = 1 + e^{2\psi} \|Du\|^2,$$

and thus,

$$(3.24) \quad 2\tilde{v}\tilde{v}_i = 2\psi_\alpha x_i^\alpha e^{2\psi} \|Du\|^2 + 2e^{2\psi} u_{ij} u^j,$$

from which we infer

$$(3.25) \quad |\tilde{v}_i u^i| \leq c \tilde{v}^3 + \tilde{v}^{-1} e^{2\psi} |u_{ij} u^i u^j|,$$

which gives the result because of (1.16). q.e.d.

We are now ready to prove the uniform boundedness of \tilde{v} .

PROPOSITION 3.7. *During the evolution the term \tilde{v} remains uniformly bounded*

$$(3.26) \quad \tilde{v} \leq c = c(\Omega, |f|, \|Df\|).$$

Proof. Let μ, λ be positive constants, where μ is supposed to be small and λ large, and define

$$(3.27) \quad \varphi = e^{\mu e^{\lambda u}},$$

where we assume without loss of generality that $1 \leq u$, otherwise replace in (3.27) u by $(u + c)$, c large enough.

We shall show that

$$(3.28) \quad w = \tilde{v}\varphi$$

is uniformly bounded if μ, λ are chosen appropriately.

In view of Lemma 3.3 and Lemma 3.5 we have

$$(3.29) \quad \dot{\varphi} - \Delta\varphi \leq c\mu\lambda e^{\lambda u}[\tilde{v}|f| + \tilde{v}^2]\varphi - \mu\lambda^2 e^{\lambda u}[1 + \mu e^{\lambda u}]\|Du\|^2\varphi,$$

from which we further deduce taking Lemma 3.4 and Lemma 3.6 into account

$$(3.30) \quad \begin{aligned} \dot{w} - \Delta w &\leq -(1 - \epsilon)\|A\|^2\tilde{v}\varphi + c[|f| + \|Df\|]\tilde{v}^2\varphi \\ &\quad + c[1 + \epsilon^{-1}]\tilde{v}^3\varphi - \mu\lambda^2 e^{\lambda u}[1 + \mu e^{\lambda u}]\tilde{v}\|Du\|^2\varphi \\ &\quad + c[1 + |f|]\mu\lambda e^{\lambda u}\tilde{v}^3\varphi + 2\mu\lambda e^{\lambda u}\|A\|e^{\psi}\|Du\|^2\varphi. \end{aligned}$$

We estimate the last term on the right-hand side by

$$(3.31) \quad \begin{aligned} 2\mu\lambda e^{\lambda u}\|A\|e^{\psi}\|Du\|^2\varphi &\leq (1 - \epsilon)\|A\|^2\tilde{v}\varphi \\ &\quad + \frac{1}{1 - \epsilon}\mu^2\lambda^2 e^{2\lambda u}\tilde{v}^{-1}e^{2\psi}\|Du\|^4\varphi, \end{aligned}$$

and conclude

$$(3.32) \quad \begin{aligned} \dot{w} - \Delta w &\leq c[|f| + \|Df\|]\tilde{v}^2\varphi + c[1 + |f|]\mu\lambda e^{\lambda u}\tilde{v}^3\varphi \\ &\quad + c[1 + \epsilon^{-1}]\tilde{v}^3\varphi + \left[\frac{1}{1 - \epsilon} - 1\right]\mu^2\lambda^2 e^{2\lambda u}\|Du\|^2\tilde{v}\varphi \\ &\quad - \mu\lambda^2 e^{\lambda u}\|Du\|^2\tilde{v}\varphi, \end{aligned}$$

where we have used that

$$(3.33) \quad e^{2\psi}\|Du\|^2 \leq \tilde{v}^2.$$

Setting $\epsilon = e^{-\lambda u}$, we then obtain

$$(3.34) \quad \begin{aligned} \dot{w} - \Delta w &\leq c[|f| + \|Df\|]\tilde{v}^2\varphi + ce^{\lambda u}\tilde{v}^3\varphi \\ &\quad + c[1 + |f|]\mu\lambda e^{\lambda u}\tilde{v}^3\varphi \\ &\quad + \left[\frac{\mu}{1 - \epsilon} - 1\right]\mu\lambda^2 e^{\lambda u}\|Du\|^2\tilde{v}\varphi. \end{aligned}$$

Now, we choose $\mu = \frac{1}{2}$ and λ_0 so large that

$$(3.35) \quad \frac{\mu}{1 - e^{-\lambda u}} \leq \frac{3}{4} \quad \forall \lambda \geq \lambda_0,$$

and infer that the last term on the right-hand side of (3.34) is less than

$$(3.36) \quad -\frac{1}{8}\lambda^2 e^{\lambda u} \|Du\|^2 \tilde{v} \varphi$$

which in turn can be estimated from above by

$$(3.37) \quad -c\lambda^2 e^{\lambda u} \tilde{v}^3 \varphi$$

at points where $\tilde{v} \geq 2$.

Thus, we conclude that for

$$(3.38) \quad \lambda \geq \max(\lambda_0, 4[1 + |f|_{\mathcal{Q}}])$$

the parabolic maximum principle, applied to w , yields

$$(3.39) \quad w \leq \text{const}(|w(0)|_{\mathcal{S}_0}, \lambda_0, |f|, \|Df\|, \Omega).$$

q.e.d.

4. C^2 -ESTIMATES

Since the mean curvature operator is a quasilinear operator, the uniform C^1 -estimates we have established in the last section also yield uniform C^2 -estimates during the evolution, but nevertheless, we would like to give an independent proof of the C^2 -estimates.

LEMMA 4.1. *During the evolution the principal curvatures of the evolution hypersurfaces $M(t)$ are uniformly bounded.*

Proof. As already mentioned in Remark 2.6, we know that $f \leq H$, thus, it is sufficient to estimate the principal curvatures from above.

Let φ be defined by

$$(4.1) \quad \varphi = \sup\{h_{ij}\eta^i\eta^j : \|\eta\| = 1\}.$$

We claim that φ is uniformly bounded.

Let $0 < T < T^*$, and $x_0 = x_0(t_0)$, with $0 < t_0 \leq T$, be a point in $M(t_0)$ such that

$$(4.2) \quad \sup_{M_0} \varphi < \sup\{\sup_{M(t)} \varphi : 0 < t \leq T\} = \varphi(x_0).$$

We then introduce a Riemannian normal coordinate system (ξ^i) at $x_0 \in M(t_0)$ such that at $x_0 = x(t_0, \xi_0)$ we have

$$(4.3) \quad g_{ij} = \delta_{ij} \quad \text{and} \quad \varphi = h_n^n.$$

Let $\tilde{\eta} = (\tilde{\eta}^i)$ be the contravariant vector field defined by

$$(4.4) \quad \tilde{\eta} = (0, \dots, 0, 1),$$

and set

$$(4.5) \quad \tilde{\varphi} = \frac{h_{ij}\tilde{\eta}^i\tilde{\eta}^j}{g_{ij}\tilde{\eta}^i\tilde{\eta}^j}.$$

$\tilde{\varphi}$ is well defined in neighbourhood of (t_0, ξ_0) , and $\tilde{\varphi}$ assumes its maximum at (t_0, ξ_0) . Moreover, at (t_0, ξ_0) we have

$$(4.6) \quad \dot{\tilde{\varphi}} = \dot{h}_n^n,$$

and the spatial derivatives do also coincide; in short, at (t_0, ξ_0) $\tilde{\varphi}$ satisfies the same differential equation (2.13) as h_n^n . For the sake of greater clarity, let us therefore treat h_n^n like a scalar and pretend that $\varphi = h_n^n$.

At (t_0, ξ_0) we have $\dot{\varphi} \geq 0$, and, in view of the maximum principle, we deduce from Lemma 2.5

$$(4.7) \quad 0 \leq -\|A\|^2 h_n^n + f|h_n^n|^2 + c[|f| + \|Df\| + \|D^2f\|][1 + |h_n^n|].$$

Thus, φ is uniformly bounded. q.e.d.

5. CONVERGENCE TO A STATIONARY SOLUTION

We are now ready to give a new proof of Theorem 2.2. Let us look at the scalar version of the flow as in (3.6)

$$(5.1) \quad \frac{\partial u}{\partial t} = -e^{-\psi}v(H - f).$$

This is a scalar parabolic differential equation defined on the cylinder

$$(5.2) \quad Q_{T^*} = [0, T^*) \times \mathcal{S}_0$$

with initial value $u(0) = u_2 \in C^{4,\alpha}(\mathcal{S}_0)$. In view of the a priori estimates, which we have established in the preceding sections, we know that

$$(5.3) \quad |u|_{2,0,\mathcal{S}_0} \leq c$$

and

$$(5.4) \quad H \text{ is uniformly elliptic in } u$$

independent of t . Thus, we can apply the known regularity results, see e.g. [11, Chapter 5.5], where even more general operators are considered, to conclude that uniform $C^{2,\alpha}$ -estimates are valid, leading further to uniform $C^{4,\alpha}$ -estimates due to the regularity results for linear operators.

Therefore, the maximal time interval is unbounded, i.e. $T^* = \infty$.

Now, integrating (5.1) with respect to t , and observing that the right-hand side is non-positive, yields

$$(5.5) \quad u(0, x) - u(t, x) = \int_0^t e^{-\psi} v(H - f) \geq c \int_0^t (H - f),$$

i.e.,

$$(5.6) \quad \int_0^\infty |H - f| < \infty \quad \forall x \in \mathcal{S}_0$$

Hence, for any $x \in \mathcal{S}_0$ there is a sequence $t_k \rightarrow \infty$ such that $(H - f) \rightarrow 0$.

On the other hand, $u(\cdot, x)$ is monotone decreasing and therefore

$$(5.7) \quad \lim_{t \rightarrow \infty} u(t, x) = \tilde{u}(x)$$

exists and is of class $C^{4,\alpha}(\mathcal{S}_0)$ in view of the a priori estimates. We, finally, conclude that \tilde{u} is a stationary solution of our problem, and that

$$(5.8) \quad \lim_{t \rightarrow \infty} (H - f) = 0.$$

To prove existence under the weaker assumptions of Theorem 2.2, we use approximation and the a priori estimate in [3, Theorem 4.1].

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